

Figure 1

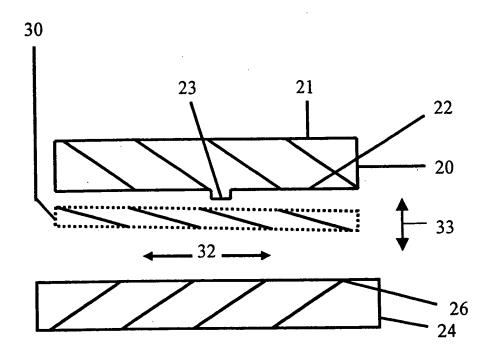


Figure 2

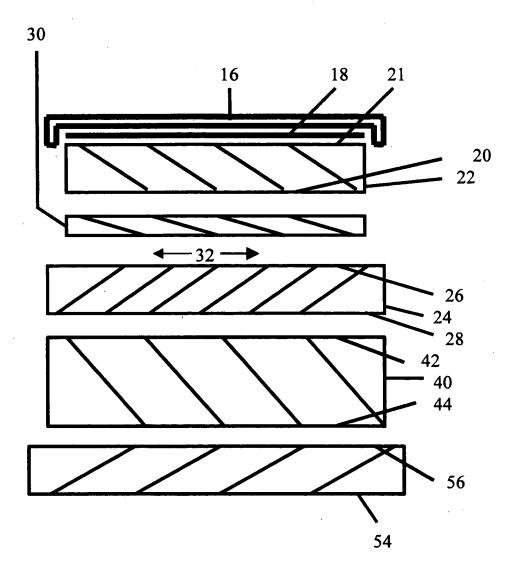


Figure 3

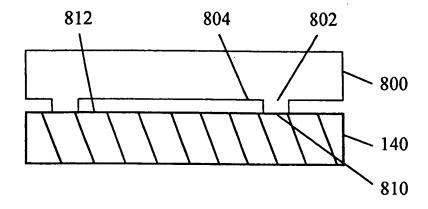
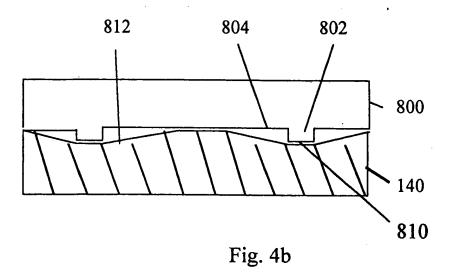


Fig. 4a



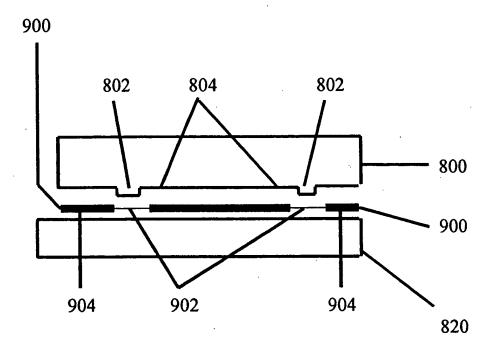


Figure 5

Figure 6

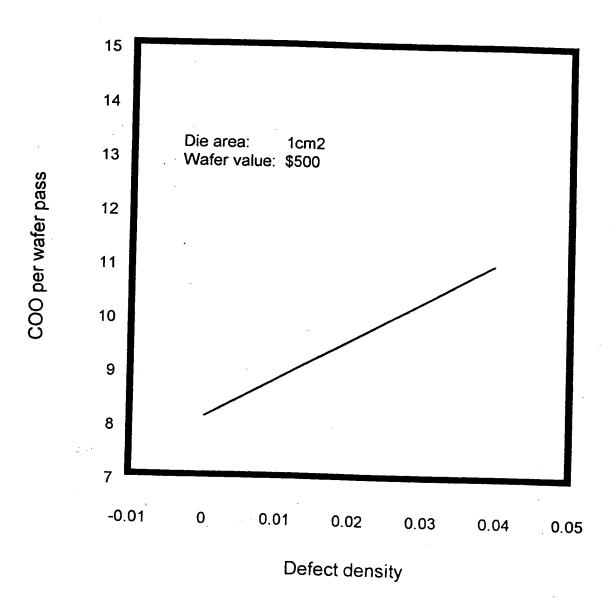


Figure 7

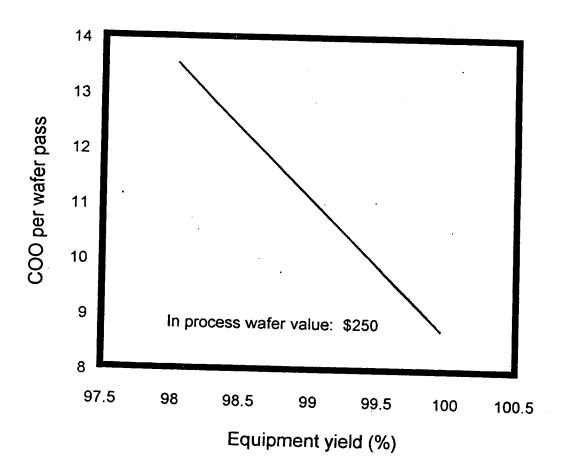


Figure 8

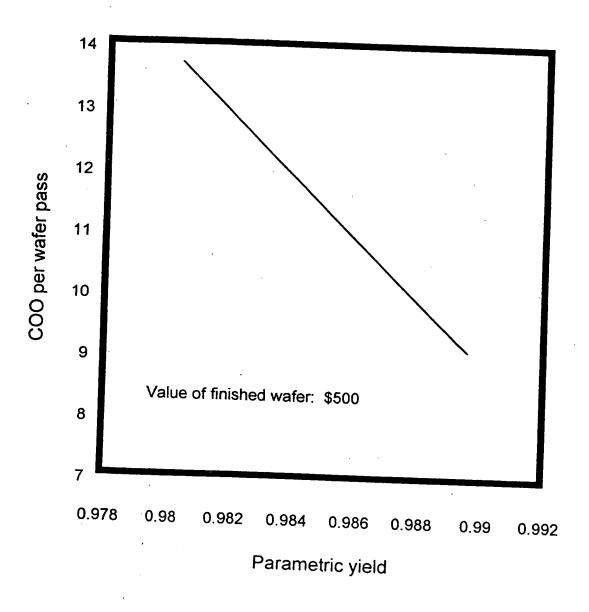
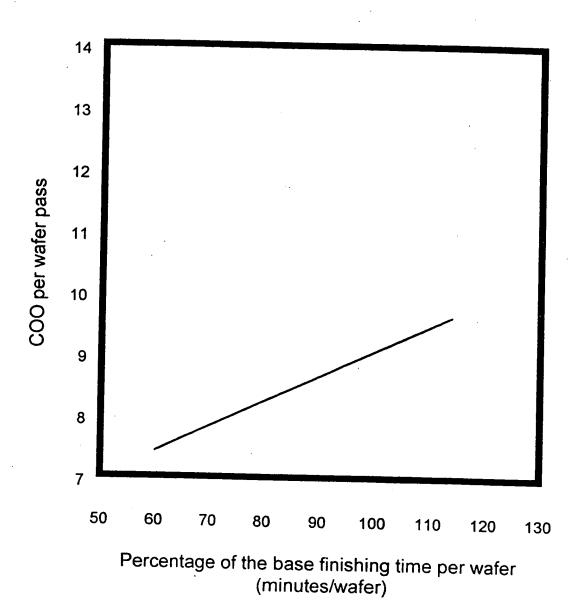


Figure 9



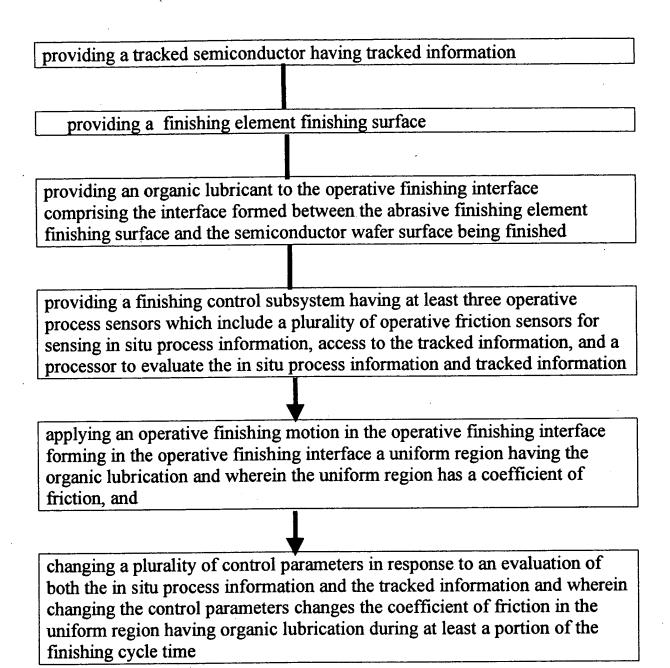


Figure 10

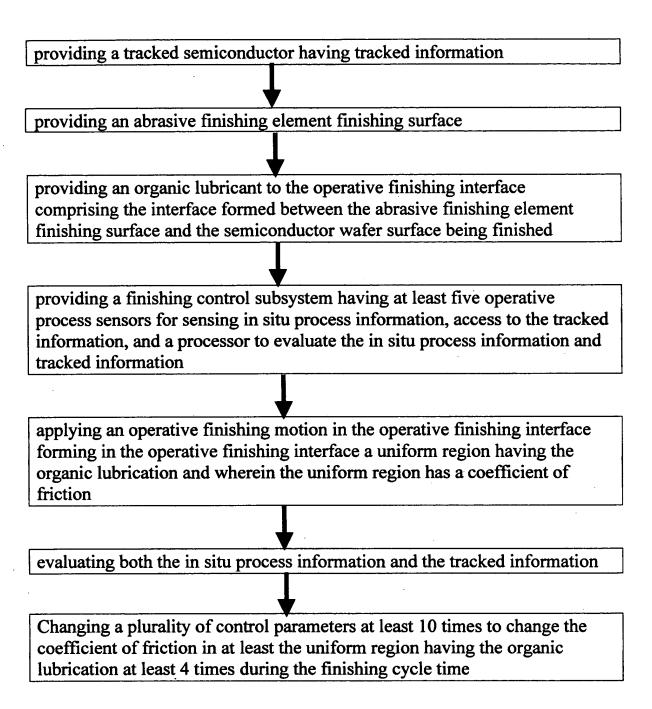


Figure 11

providing the tracked semiconductor wafer having tracked information providing a finishing surface providing a finishing aid to an interface formed between the finishing surface and the semiconductor wafer surface providing a finishing control subsystem having at least three operative process sensors for sensing in situ process information during the finishing cycle time; access to the tracked information; and a processor to evaluate the in situ process information and the tracked information applying an operative finishing motion in the interface forming at least one region having the finishing aid and wherein the at least one region has a tangential force of friction; and changing a plurality of control parameters in response to an evaluation of both the in situ process information sensed with the at least three operative process sensors and the tracked information and wherein changing the control parameters changes the tangential force of friction in the at least one region having the finishing aid during at least a portion of the finishing cycle time.

Figure 12

providing a semiconductor wafer

providing a finishing surface

providing a finishing aid proximate the semiconductor wafer and wherein the finishing aid comprises a reactive finishing aid which reacts with at least portion of the semiconductor wafer surface changing the finishing rate in angstroms per minute when compared to the finishing rate under identical finishing conditions but in the absence of the reactive finishing aid

providing at least one finishing control subsystem having at least three operative process sensors, at least one processor, and a controller and wherein the at least one processor for processing (i) tracked information, and (ii) historical performance

applying an operative finishing motion to an interface between the semiconductor wafer and the finishing surface and wherein the interface includes the finishing aid; and

sensing an in situ finishing information with the at least three operative process sensors during a finishing cycle time

evaluating a multiplicity finishing information, and each having varying effects on the finishing with the finishing aid

determining a change for at least two process control parameter using (i) tracked information, (ii) historical performance, (iii) the in situ finishing information, and (iv) evaluating the multiplicity of finishing information

changing the at least two control parameters to change the finishing rate measured in angstroms per minute in the at least portion of the semiconductor wafer during the finishing cycle time

Figure 13

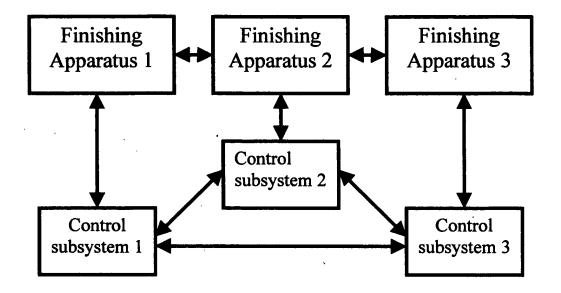


Figure 14a

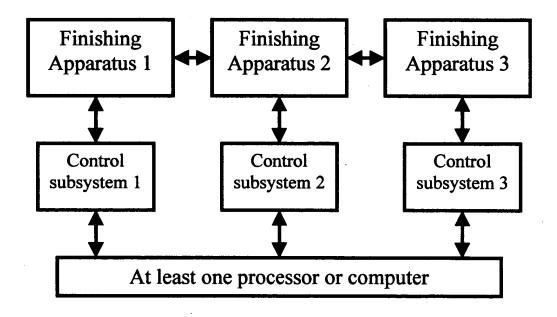


Figure 14b